

Chapter 4

Vector Spaces

§4.6 Rank of a Matrix II

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Goals

Suppose A is a $m \times n$ matrix

- ▶ The **row space** and **column space** of A will be defined, as a vector space.
- ▶ **$\text{rank}(A)$** will be re-defined. *This will agree with $\text{rank}(A)$ defined in the the chapter on determinants.*
- ▶ Then **Null space $N(A)$** of A will be defined, as a vector space.
- ▶ It will be proved $\text{rank}(A) + \dim(N(A)) = n$.

Row and Column vectors

Suppose A is a $m \times n$ matrix.

- ▶ The n -tuples corresponding to the rows of A are called **row vectors** of A . So, the row vectors of A are in $\mathbb{R}^n$.
- ▶ The m -tuples corresponding to the columns of A are called **column vectors** of A . So, the column vectors of A are in $\mathbb{R}^m$.

Row and Column vectors

Suppose

$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \cdots & \cdots & \cdots & \cdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{pmatrix} \quad \text{Then} \quad \begin{matrix} \text{row vectors of } A \\ (a_{11}, a_{12}, \cdots, a_{1n}) \\ (a_{21}, a_{22}, \cdots, a_{2n}) \\ \cdots \\ (a_{m1}, a_{12}, \cdots, a_{mn}) \end{matrix}$$

The column vectors of A are

$$\begin{pmatrix} a_{11} \\ a_{21} \\ \cdots \\ a_{m1} \end{pmatrix}, \begin{pmatrix} a_{12} \\ a_{22} \\ \cdots \\ a_{m2} \end{pmatrix}, \cdots, \begin{pmatrix} a_{1n} \\ a_{2n} \\ \cdots \\ a_{mn} \end{pmatrix}$$

Row and Column Spaces

Suppose A is a $m \times n$ matrix, as above.

- ▶ The **row space** of A is defined to be the subspace of $\mathbb{R}^n$ spanned by row vectors of A .
(*In this case, think of vectors in $\mathbb{R}^n$, as rows.*)
- ▶ The **column space** of A is defined to be the subspace of $\mathbb{R}^n$ spanned by column vectors of A .
(*In this case, think of vectors in $\mathbb{R}^n$, as columns.*)

Continued

So,

► *row – space*(A) =

$$\text{span} \left(\begin{pmatrix} (a_{11}, a_{12}, \dots, a_{1n}) \\ (a_{21}, a_{22}, \dots, a_{2n}) \\ \dots \\ (a_{m1}, a_{12}, \dots, a_{mn}) \end{pmatrix} \right) \subseteq \mathbb{R}^n.$$

► *column – space*(A) =

$$\text{span} \left(\left(\begin{pmatrix} a_{11} \\ a_{21} \\ \dots \\ a_{m1} \end{pmatrix}, \begin{pmatrix} a_{12} \\ a_{22} \\ \dots \\ a_{m2} \end{pmatrix}, \dots, \begin{pmatrix} a_{1n} \\ a_{2n} \\ \dots \\ a_{mn} \end{pmatrix} \right) \right) \subseteq \mathbb{R}^m.$$

Some Properties: Theorem 4.6.1

Theorem 4.6.1 Suppose A, B are two $m \times n$ matrices.

- ▶ If A and B are row equivalent then,
 $\text{rowSpace}(A) = \text{rowSpace}(B)$.
- ▶ If A and B are column equivalent then,
 $\text{columnSpace}(A) = \text{columnSpace}(B)$.

Remark. The properties of row-spaces and column-spaces would be analogous.

Continued

Proof. To prove the first statement, assume A and B are row equivalent. We can write $B = E_k E_{k-1} \cdots E_2 E_1 A$, where $E_1, \dots, E_k$ are elementary row matrices. Inductively, we prove

$$\begin{aligned} \text{rowspace}(A) &= \text{rowspace}(E_1 A) = \text{rowspace}(E_2 E_1 A) = \cdots \\ &= \text{rowspace}(E_{k-1} \cdots E_2 E_1 A) = \text{rowspace}(B). \end{aligned}$$

So, it is enough to prove $\text{rowspace}(A) = \text{rowspace}(EA)$, where E is an elementary row matrix.

Continued

- ▶ If E switches two rows of I_m , EA switches two rows of A .
Hence $\text{rowspace}(A) = \text{rowspace}(EA)$.
- ▶ If E is obtained by multiplying a row of I_m by $c \neq 0$,
 EA is obtained from multiplying the same row by c .
Hence $\text{rowspace}(EA) \subseteq \text{rowspace}(A)$.
Now, A is obtained, from EA by multiplying the
same row of EA by $\frac{1}{c}$.
So, $\text{rowspace}(A) \subseteq \text{rowspace}(EA)$, and
 $\text{rowspace}(EA) = \text{rowspace}(A)$.

Continued

- ▶ If E is obtained by adding c times a row of I_m , then EA is obtained, from A , by adding c times a row of A , to another. So, all rows of EA are either same or a linear combination of rows of A . So, $\text{rowspace}(EA) \subseteq \text{rowspace}(A)$.
 Again, process is reversible. So, $\text{rowspace}(A) \subseteq \text{rowspace}(EA)$. Therefore, $\text{rowspace}(EA) = \text{rowspace}(A)$.

This completes the proof of the statement on row spaces.

Continued

Now, suppose B is column equivalent to A .
Then B^T is row equivalent to A^T . We have

$$\begin{aligned} \text{Columnspace}(A) &= \text{rowspace}(A^T) = \text{rowspace}(B^T) \\ &= \text{Columnspace}(B) \end{aligned}$$

This completes the proof of the statement on column spaces.



Basis of Row Space: Theorem 4.6.2

(**Basis of Row Space**) Suppose A, B are two $m \times n$ matrices. If B is in row-echelon form then the **non-zero rows of B** forms a **basis** of $\text{row} - \text{space}(A)$ (which is same as $\text{row} - \text{space}(B)$).

Proof. Note that the nonzero rows of a matrix in Echelon form are linearly independent. Now, the theorem follows from Theorem 4.6.1. ■

Theorem 4.6.3

Let A be $m \times n$ matrix. Then

$$\dim(\text{rowSpace}(A)) = \dim(\text{columnSpace}(A)).$$

Proof. Write

$$A = \begin{pmatrix} \mathbf{r}_1 \\ \mathbf{r}_2 \\ \dots \\ \mathbf{r}_m \end{pmatrix} = \begin{pmatrix} \mathbf{c}_1 & \mathbf{c}_2 & \dots & \mathbf{c}_n \end{pmatrix}$$

where $\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_m$ are the rows of A and
 $\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_n$ are the columns of A

Continued

Assume $\dim(\text{rowspace}(A)) = k$.

Let $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k$ be a basis of $\text{rowspace}(A)$
(and think of $\mathbf{u}_i$ as row matrices). We can write

$$\begin{cases} \mathbf{r}_1 = \alpha_{11}\mathbf{u}_1 + \alpha_{12}\mathbf{u}_2 + \cdots + \alpha_{1k}\mathbf{u}_k \\ \mathbf{r}_2 = \alpha_{21}\mathbf{u}_1 + \alpha_{22}\mathbf{u}_2 + \cdots + \alpha_{2k}\mathbf{u}_k \\ \quad \quad \quad \dots \\ \mathbf{r}_m = \alpha_{m1}\mathbf{u}_1 + \alpha_{m2}\mathbf{u}_2 + \cdots + \alpha_{mk}\mathbf{u}_k \end{cases} \quad \text{where } \alpha_{ij} \in \mathbb{R}.$$

Continued

We rewrite it in matrix form:

$$A = \begin{pmatrix} \mathbf{r}_1 \\ \mathbf{r}_2 \\ \dots \\ \mathbf{r}_m \end{pmatrix} = \begin{pmatrix} \alpha_{11} & \alpha_{12} & \dots & \alpha_{1k} \\ \alpha_{21} & \alpha_{22} & \dots & \alpha_{2k} \\ \dots & \dots & \dots & \dots \\ \alpha_{m1} & \alpha_{m2} & \dots & \alpha_{mk} \end{pmatrix} \begin{pmatrix} \mathbf{u}_1 \\ \mathbf{u}_2 \\ \dots \\ \mathbf{u}_k \end{pmatrix}$$

Let me caution you that, on right hand side, we are multiplying a matrix with real number entries , with a matrix whose entries are row vectors. However, it works. You can accept or trust it or try to convince yourself.

Continued

Apply Transpose operation to the above equation:

$$A^T = \begin{pmatrix} \mathbf{u}_1^T & \mathbf{u}_2^T & \cdots & \mathbf{u}_k^T \end{pmatrix} \begin{pmatrix} \alpha_{11} & \alpha_{21} & \cdots & \alpha_{m1} \\ \alpha_{12} & \alpha_{22} & \cdots & \alpha_{m2} \\ \cdots & \cdots & \cdots & \cdots \\ \alpha_{1k} & \alpha_{2k} & \cdots & \alpha_{mk} \end{pmatrix} \quad (1)$$

We denote the rows of the matrix (α_{ij}) by $\mathbf{w}_1, \mathbf{w}_2, \cdots, \mathbf{w}_k$. So,

$$\begin{pmatrix} \alpha_{11} & \alpha_{21} & \cdots & \alpha_{m1} \\ \alpha_{12} & \alpha_{22} & \cdots & \alpha_{m2} \\ \cdots & \cdots & \cdots & \cdots \\ \alpha_{1k} & \alpha_{2k} & \cdots & \alpha_{mk} \end{pmatrix} = \begin{pmatrix} \mathbf{w}_1 \\ \mathbf{w}_2 \\ \cdots \\ \mathbf{w}_k \end{pmatrix}$$

Continued

Note, $(\mathbf{u}_1^T \ \mathbf{u}_2^T \ \cdots \ \mathbf{u}_k^T)$ is an $n \times k$ matrix. So, we write

$$(\mathbf{u}_1^T \ \mathbf{u}_2^T \ \cdots \ \mathbf{u}_k^T) = \begin{pmatrix} \beta_{11} & \beta_{21} & \cdots & \beta_{1k} \\ \beta_{12} & \beta_{22} & \cdots & \beta_{2k} \\ \cdots & \cdots & \cdots & \cdots \\ \beta_{n1} & \beta_{n2} & \cdots & \beta_{nk} \end{pmatrix} \text{ where } \beta_{ij} \in \mathbb{R}.$$

Continued

So, Equation 1 can be written as

$$\begin{pmatrix} \mathbf{c}_1^T \\ \mathbf{c}_2^T \\ \dots \\ \mathbf{c}_n^T \end{pmatrix} = \begin{pmatrix} \beta_{11} & \beta_{12} & \dots & \beta_{1k} \\ \beta_{21} & \beta_{22} & \dots & \beta_{2k} \\ \dots & \dots & \dots & \dots \\ \beta_{n1} & \beta_{n2} & \dots & \beta_{nk} \end{pmatrix} \begin{pmatrix} \mathbf{w}_1 \\ \mathbf{w}_2 \\ \dots \\ \mathbf{w}_k \end{pmatrix}$$

It follows $\begin{cases} \mathbf{c}_1^T = \beta_{11}\mathbf{w}_1 + \beta_{12}\mathbf{w}_2 + \dots + \beta_{1k}\mathbf{w}_k \\ \mathbf{c}_2^T = \beta_{21}\mathbf{w}_1 + \beta_{22}\mathbf{w}_2 + \dots + \beta_{2k}\mathbf{w}_k \\ \dots \\ \mathbf{c}_n^T = \beta_{n1}\mathbf{w}_1 + \beta_{n2}\mathbf{w}_2 + \dots + \beta_{nk}\mathbf{w}_k \end{cases}$

Continued

$$\text{Hence } \begin{cases} \mathbf{c}_1 = \beta_{11}\mathbf{w}_1^T + \beta_{12}\mathbf{w}_2^T + \cdots + \beta_{1k}\mathbf{w}_k^T \\ \mathbf{c}_2 = \beta_{21}\mathbf{w}_1^T + \beta_{22}\mathbf{w}_2^T + \cdots + \beta_{2k}\mathbf{w}_k^T \\ \quad \quad \quad \dots \\ \mathbf{c}_n = \beta_{n1}\mathbf{w}_1^T + \beta_{n2}\mathbf{w}_2^T + \cdots + \beta_{nk}\mathbf{w}_k^T \end{cases}$$

So,

$$\text{ColumnSpan}(A) = \text{span}\{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_n\} \subseteq \text{span}\{\mathbf{w}_1^T, \mathbf{w}_2^T, \dots, \mathbf{w}_k^T\}$$

Therefore, by Corollary 4.5.7

$$\dim(\text{ColumnSpan}(A)) \leq k = \dim(\text{rowSpace}(A))$$

Continued

Now,

$$\dim(\text{rowSpace}(A)) = \dim(\text{ColumnSpace}(A^T)) \leq$$

$$\dim(\text{rowSpace}(A^T)) = \dim(\text{ColumnSpace}(A))$$

Hence

$$\dim(\text{ColumnSpan}(A)) = k = \dim(\text{rowSpace}(A))$$

The proof is complete. ■

Rank of a Matrix:

Definition. Let A be $m \times n$ matrix. Then the **rank** of A (written as $\text{rank}(A)$) is defined to be the dimension of the row space of A (equivalently, dimension of the column space of A).

$$\text{rank}(A) := \dim(\text{rowSpace}(A))$$

By Theorem 4.6.3, we also have,

$$\begin{cases} \text{rank}(A) = \dim(\text{ColumnSpace}(A)) \\ \text{rank}(A^t) = \text{rank}(A) \end{cases}$$

Two Definitions of Rank

- ▶ For a matrix A , in chapter 3 (on Determinants), we defined

$$\text{rank}(A) = \max \{k : \exists \text{ a minor } M \text{ of order } k, \exists M \neq 0\}$$

- ▶ **Theorem.** These two definitions of $\text{rank}(A)$ coincide. You can compute $\text{rank}(A)$, in either way.

Null Space of a Matrix

Definitions Let A be an $m \times n$ matrix.

The **Null Space** $N(A)$ is defined to be the set of all the solutions of the homogeneous system of equations $A\mathbf{x} = \mathbf{0}$.

$$N(A) = \{\mathbf{x} \in \mathbb{R}^n : A\mathbf{x} = \mathbf{0}\}.$$

The null space $N(A)$ is also called the **solution space** of $A\mathbf{x} = \mathbf{0}$.

Theorem 4.6.4

Suppose A is an $m \times n$ matrix.

Then the null space $N(A)$ is a subspace of $\mathbb{R}^n$.

Proof. By definition $N(A) = \{\mathbf{x} \in \mathbb{R}^n : A\mathbf{x} = \mathbf{0}\}$.

Note that $\mathbf{0}$ is a solution of $A\mathbf{x} = \mathbf{0}$, $\mathbf{0} \in N(A)$
(called the trivial solution). So, $N(A)$ is **nonempty**.

Continued

Now, we only need to show that $N(A)$ is closed under addition and scalar multiplication. Suppose $\mathbf{x}, \mathbf{y} \in N(A)$ and c is a scalar. Then

$$A(\mathbf{x} + \mathbf{y}) = A\mathbf{x} + A\mathbf{y} = \mathbf{0} + \mathbf{0} = \mathbf{0}$$

So, $\mathbf{x} + \mathbf{y} \in N(A)$. So, $N(A)$ is closed under addition. Also,

$$A(c\mathbf{x}) = cA(\mathbf{x}) = c\mathbf{0} = \mathbf{0}$$

So, $c\mathbf{x} \in N(A)$. So, $N(A)$ is closed under scalar multiplication. Therefore $N(A)$ is a subspace of $\mathbb{R}^n$.

The proof is complete.

Definition: Nullity

Let A be an $m \times n$ matrix.

Then **nullity of A** (written, $\text{Nullity}(A)$) is defined to be the dimension of the null space of A . Notationally,

$$\text{Nullity}(A) = \dim(N(A)).$$

- ▶ The right side makes sense, because $N(A)$ is subspace.
- ▶ Now, given a matrix A , we have associated two numbers:
(1) $\text{rank}(A)$ and (2) $\text{Nullity}(A)$.

Theorem 4.6.5

Let A be $m \times n$ matrix.

► Then

$$\text{rank}(A) + \text{Nullity}(A) = n. \quad \text{The number of columns}$$

- This means, if rank of A is r , then the dimension of the solution space of $A\mathbf{x} = \mathbf{0}$ is $n - r$.
- Note n is the number of variables in the system $A\mathbf{x} = \mathbf{0}$.

Proof.

Suppose A is row equivalent to B , which is in row Echelon form. We have seen (1) $\text{rank}(A) = \text{rank}(B)$, (2) $N(A) = N(B)$. So, $\text{Nullity}(B) = \text{Nullity}(A)$.

So, it is enough to prove the theorem, when A is in row Echelon form. In this case,

- ▶ $\text{rank}(A) = r$ is the number of non zero rows of A .
- ▶ Inspecting the system in Echelon form, it follows $\dim(N(A)) = n - r$. (*We skip the details.*)



Solutions of Linear Systems

Let $A\mathbf{x} = \mathbf{b}$ be a system of linear m equations, in n variables.

Remarks:

- ▶ Here A is a $m \times n$ matrix.
- ▶ For a homogeneous system $A\mathbf{x} = \mathbf{0}$, set of its solutions is the null space $N(A)$, which is a subspace of $\mathbb{R}^n$.
- ▶ If the system $A\mathbf{x} = \mathbf{b}$ is non-homogeneous (i.e. $\mathbf{b} \neq \mathbf{0}$), then the set of solutions is not a subspace of $\mathbb{R}^n$. This is because the zero $\mathbf{0}$ is not a solution of such a system.
- ▶ However, the solutions of a system $A\mathbf{x} = \mathbf{b}$ is related to the solutions space of the corresponding homogeneous system $A\mathbf{x} = \mathbf{0}$, the null space $N(A)$.

Theorem 4.6.6: Solutions of Linear Systems

Let $A\mathbf{x} = \mathbf{b}$ be a system of linear m equations, in n variables. Fix a solution $\mathbf{x}_p$ of $A\mathbf{x} = \mathbf{b}$, to be called a "**particular solution**". Then any solution of $A\mathbf{x} = \mathbf{b}$ can be written as

$$\mathbf{x} = \mathbf{x}_p + \mathbf{x}_h \quad \mathbf{x}_h \in N(A).$$

Proof. Suppose $A\mathbf{x} = \mathbf{b}$. Write $\mathbf{x}_h = \mathbf{x} - \mathbf{x}_p$. Then

$$A\mathbf{x}_h = A\mathbf{x} - A\mathbf{x}_p = \mathbf{b} - \mathbf{b} = \mathbf{0}. \text{ So, } \mathbf{x}_h \in N(A), \text{ and } \mathbf{x} = \mathbf{x}_p + \mathbf{x}_h.$$

This completes the proof. ■

Theorem 4.6.7: Consistent System

A system $A\mathbf{x} = \mathbf{b}$ is consistent, if $\mathbf{b} \in \text{ColumnSpace}(A)$.

Proof. If the system has a solution $\mathbf{x}$, then $\mathbf{b}$ is linear combination of the columns: $\mathbf{b} = x_1(\text{First} - \text{Column}) + x_2(\text{second} - \text{Column}) + \cdots + x_n(\text{First} - \text{Column})$. The proof is complete. 

A Summary

Let A be a square matrix of order n . The following conditions are equivalent:

1. A is invertible.
2. $A\mathbf{x} = \mathbf{b}$ has a unique solution.
3. $A\mathbf{x} = \mathbf{0}$ has only trivial solution.
4. A is row equivalent to I_n .
5. $|A| \neq 0$.
6. $\text{rank}(A) = n$.
7. The n row vectors of A are linearly independent.
8. The n column vectors of A are linearly independent.

Continued

- ▶ This (the last frame) is an update of a list given in §3.3.
- ▶ Last three conditions were added to the old list.
- ▶ From definition of rank, it follows

$$(6) \iff (7) \iff (8).$$

Also,

$$(4) \iff (7).$$

This completes the proof. ■

Basis of row spaces

Suppose A is an $m \times n$ matrix.

- By Theorem 4.6.1, if B is in row-echelon form (or in reduced row-echelon form) and is row equivalent to A then the **non-zero rows of B** forms a **basis** of *row – space*(A)

Remark. In fact, if B is like a row-echelon matrix, but **without "leading 1"**, same works.

We will call them **essentially in row Echelon form**.

This sometimes help, avoiding decimals.

Example 4.6.1

Let $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 7 & -15 \\ 2 & 6 & -8 \end{bmatrix}$. Find basis of the row space of A .

1. Find a basis of the row space of A .
2. Find the rank of A .

Solution.

Use "ref" in TI-84 ("ref")l.

$$B = \begin{bmatrix} 1 & \frac{7}{2} & -\frac{15}{2} \\ 0 & 1 & -7 \\ 0 & 0 & 0 \end{bmatrix}$$

A basis of the row space : $S = \left\{ \left(1, \frac{7}{2}, -\frac{15}{2} \right), (0, 1, -7) \right\}$

So, $\text{rank}(A) = \dim(\text{rowSpace}(A)) = 2.$

Example 4.6.2

Let A be as in Example 4.6.1. Now find a basis of the column space of A .

Solution. Column space of A is the row space of A^T (written as rows). We have

$$A^T = \begin{pmatrix} 1 & 2 & 2 \\ 2 & 7 & 6 \\ 3 & -15 & -8 \end{pmatrix}$$

I want to solve it by hand, without TI-84. TI-84 quickly brings in nonterminating decimal numbers, which is inconvenient.

Continued

Solution: Subtract 2 times first row from second and three times first row from third:

$$\begin{pmatrix} 1 & 2 & 2 \\ 0 & 3 & 2 \\ 0 & -21 & -14 \end{pmatrix}$$

Now subtract 7 times second row from third:

$$\begin{pmatrix} 1 & 2 & 2 \\ 0 & 3 & 2 \\ 0 & 0 & 0 \end{pmatrix} \quad \text{This is essentially in row Echelon form.}$$

Continued

So, a basis of $\text{rowspace}(A^T)$ is

$$S = \{(1, 2, 2), (0, 3, 2)\}$$

So, a basis of the Column Space of A is

$$\left\{ \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 3 \\ 4 \end{pmatrix} \right\}$$

Example 4.6.3

$$\text{Let } A = \begin{pmatrix} 8 & 0 & 4 & 6 & 2 \\ 3 & 1 & 0 & -2 & -1 \\ 9 & 2 & 4 & 4 & 0 \\ 5 & 2 & 2 & -2 & -1 \\ 3 & 0 & 0 & -2 & -1 \end{pmatrix}$$

1. Find a basis of the row space of A
2. Find the rank of A .
3. Find the Nullity of A

Proof. We reduce A to an, **essentially**, row echelon form.
Divide first row by two:

$$\begin{pmatrix} 4 & 0 & 2 & 3 & 1 \\ 3 & 1 & 0 & -2 & -1 \\ 9 & 2 & 4 & 4 & 0 \\ 5 & 2 & 2 & -2 & -1 \\ 3 & 0 & 0 & -2 & -1 \end{pmatrix}$$

Subtract 2 times 1st row of A from 3rd, then switch 1st and 3rd rows:

$$\begin{pmatrix} 4 & 0 & 2 & 3 & 1 \\ 3 & 1 & 0 & -2 & -1 \\ 1 & 2 & 0 & -2 & -2 \\ 5 & 2 & 2 & -2 & -1 \\ 3 & 0 & 0 & -2 & -1 \end{pmatrix} \mapsto \begin{pmatrix} 1 & 2 & 0 & -2 & -2 \\ 3 & 1 & 0 & -2 & -1 \\ 4 & 0 & 2 & 3 & 1 \\ 5 & 2 & 2 & -2 & -1 \\ 3 & 0 & 0 & -2 & -1 \end{pmatrix}$$

(1) Subtract 3 times first row from second and fifth, and 4 times first row from third and 5 times first from fourth; (2) then subtract fifth row from second:

$$\begin{pmatrix} 1 & 2 & 0 & -2 & -2 \\ 0 & -5 & 0 & 4 & 5 \\ 0 & -8 & 2 & 11 & 9 \\ 0 & -8 & 2 & 8 & 9 \\ 0 & -6 & 0 & 4 & 5 \end{pmatrix} \mapsto \begin{pmatrix} 1 & 2 & 0 & -2 & -2 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & -8 & 2 & 11 & 9 \\ 0 & -8 & 2 & 8 & 9 \\ 0 & -6 & 0 & 4 & 5 \end{pmatrix}$$

Add 8 times 2^{nd} row to 3^{rd} , 4^{th} and 6 times 2^{nd} row to 5^{th} :

$$\begin{pmatrix} 1 & 2 & 0 & -2 & -2 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 2 & 11 & 9 \\ 0 & 0 & 2 & 8 & 9 \\ 0 & 0 & 0 & 4 & 5 \end{pmatrix}$$

Subtract 3^{rd} row from 4^{th} :

$$\begin{pmatrix} 1 & 2 & 0 & -2 & -2 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 2 & 11 & 9 \\ 0 & 0 & 0 & -3 & 0 \\ 0 & 0 & 0 & 4 & 5 \end{pmatrix}$$

Add $\frac{4}{3}$ times 4^{th} row to 5^{th} :

$$\begin{pmatrix} 1 & 2 & 0 & -2 & -2 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 2 & 11 & 9 \\ 0 & 0 & 0 & -3 & 0 \\ 0 & 0 & 0 & 0 & 5 \end{pmatrix}$$

The matrix is, **essentially**, in row Echelon form. So, its nonzero vectors form a basis of the $rowspace(A)$.

So, a basis of the row space of A is:

$$S = \left\{ \begin{array}{l} (1, 2, 0, -2, -2), \\ (0, 1, 0, 0, 0), \\ (0, 0, 2, 11, 9), \\ (0, 0, 0, -3, 0), \\ (0, 0, 0, 0, 5) \end{array} \right\}$$

So,

$$\begin{cases} \text{rank}(A) = \dim(\text{row space}) = 5, \\ \text{Nullity}(A) = 5 - 5 = 0 \end{cases}$$

Example 4.6.3a

We modify the above problem, to create a new problem.

$$\text{Let } A = \begin{pmatrix} 8 & 0 & 4 & 6 & 2 \\ 3 & 1 & 0 & -2 & -1 \\ 9 & 2 & 4 & 4 & 0 \end{pmatrix}$$

1. Find a basis of the row space of A
2. Find the rank of A .
3. Find the Nullity of A

Proof. We reduce A to an, **essentially**, row echelon form.
Divide first row by two:

$$\begin{pmatrix} 4 & 0 & 2 & 3 & 1 \\ 3 & 1 & 0 & -2 & -1 \\ 9 & 2 & 4 & 4 & 0 \end{pmatrix}$$

Subtract 2^{nd} row from 1^{st} and subtract 3 times 2^{nd} row from
from third:

$$\begin{pmatrix} 1 & -1 & 2 & 5 & 2 \\ 3 & 1 & 0 & -2 & -1 \\ 0 & -1 & 4 & 10 & 3 \end{pmatrix}$$

Switch 2^{nd} and 3^{rd} rows:

$$\begin{pmatrix} 1 & -1 & 2 & 5 & 2 \\ 0 & -1 & 4 & 10 & 3 \\ 3 & 1 & 0 & -2 & -1 \end{pmatrix}$$

Subtract 3 times 1^{st} from 3^{rd} :

$$\begin{pmatrix} 1 & -1 & 2 & 5 & 2 \\ 0 & -1 & 4 & 10 & 3 \\ 0 & 4 & -6 & -17 & -7 \end{pmatrix}$$

Add four times 2^{nd} to 3^{rd} :

$$\begin{pmatrix} 1 & -1 & 2 & 5 & 2 \\ 0 & -1 & 4 & 10 & 3 \\ 0 & 0 & 10 & -23 & 5 \end{pmatrix}$$

The matrix above is, **essentially**, in row Echelon form. So, its nonzero vectors form a basis of the $\text{row space}(A)$.
So, a basis of the row space of A is:

$$S = \left\{ \begin{pmatrix} 1, -1, 2, 5, 2 \\ 0, -1, 4, 10, 3 \\ 0, 0, 10, -23, 5 \end{pmatrix} \right\}$$

So,

$$\begin{cases} \text{rank}(A) = \dim(\text{row space}) = 3, \\ \text{Nullity}(A) = 5 - 3 = 2 \end{cases}$$

Basis of subspaces

Suppose V is subspace of $\mathbb{R}^n$, spanned by a few given vectors.
To find a basis of V do the following:

- ▶ Form a matrix A with these vectors, as rows.
- ▶ Then, row space of A is V .
- ▶ A basis of the row space would be a basis of V .

Example 4.6.4

Let $S = \{(3, 2, 2), (6, 5, -1), (1, 1, -1)\}$. Find a basis of $\text{span}(S)$, and $\dim(\text{span}(S))$.

Solution. Form the matrix A , with these rows.

$$A = \begin{pmatrix} 3 & 2 & 2 \\ 6 & 5 & -1 \\ 1 & 1 & -1 \end{pmatrix}$$

Solution: We try to reduce the matrix, to a matrix **essentially** in Echelon form.

Continued

Switch first and third rows:

$$\begin{pmatrix} 1 & 1 & -1 \\ 6 & 5 & -1 \\ 3 & 2 & 2 \end{pmatrix}$$

Subtract 6 times 1st row, from 2nd and 3 times 1st row, from 3rd:

$$\begin{pmatrix} 1 & 1 & -1 \\ 0 & -1 & 5 \\ 0 & -1 & 5 \end{pmatrix}$$

Continued

Subtract 2^{nd} row from 3^{rd} :

$$\begin{pmatrix} 1 & 1 & -1 \\ 0 & -1 & 5 \\ 0 & 0 & 0 \end{pmatrix}$$

The matrix is essentially in row Echelon form. So,

$$\begin{cases} \text{Basis of } \text{span}(S) = \{(1, 1, -1), (0, -1, 5)\} \\ \dim(\text{span}(S)) = 2 \end{cases}$$

Example 4.6.5

Let
$$A = \begin{pmatrix} 7 & 14 & -21 \\ 3 & 6 & -9 \\ -4 & -8 & 12 \end{pmatrix}$$

- ▶ Give basis of the row space of A
- ▶ Compute $\text{rank}(A)$
- ▶ Compute $\text{Nullity}(A)$
- ▶ Give a basis of the null space $N(A)$.

Solution. First, reduce A to an, essentially, row echelon form.

Continued

Subtract 2 times 2nd row of A from first:

$$\begin{pmatrix} 1 & 2 & -3 \\ 3 & 6 & -9 \\ -4 & -8 & 12 \end{pmatrix}$$

Subtract 3 times first row from second and, add 4 times first row to third:

$$\begin{pmatrix} 1 & 2 & -3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

This matrix is essentially in row echelon form.

Continued

- ▶ So, a Basis of the row space of A is $\{(1, 2, -3)\}$
- ▶ $\text{rank}(A) = 1$
- ▶ $\text{Nullity}(A) = 3 - 1 = 2$
- ▶ To compute $N(A)$ and a basis of $N(A)$, we solve the homogeneous system for the above reduced matrix, which we do in the next frame.

Continued

The null space is the solution of the system, of one equation:

$$x + 2y - 3z = 0, \quad \text{Or} \quad x = 3z - 2y$$

$$\text{With } y = t, \quad z = s, \quad x = 3s - 2t$$

$$\text{So, } N(A) = \left\{ \begin{pmatrix} 3s - 2t \\ t \\ s \end{pmatrix} : t, s \in \mathbb{R} \right\}$$

Continued

Two comments:

- ▶ We already know, $\text{nullity}(A) = 2$. So, the basis of $N(A)$ would have two vectors.
- ▶ **Intuitively**, two bases will be obtained by taking $t = 1, s = 0$ and $t = 0, s = 1$.

A basis of $N(A)$ is:

$$\left\{ \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ 0 \\ 1 \end{pmatrix} \right\}$$

Example 4.6.6

Let
$$A = \begin{pmatrix} 1 & 2 & 3 & 0 \\ 4 & -1 & 7 & 4 \\ 2 & 1 & 5 & 2 \\ 1 & 1 & 2 & 0 \end{pmatrix}$$

- ▶ Give basis of the row space of A
- ▶ Compute $\text{rank}(A)$
- ▶ Compute $\text{Nullity}(A)$
- ▶ Give a basis of the null space $N(A)$.

Continued

Solution. First, reduce A to an, essentially, row echelon form. Let me remind you that I avoided using TI-84, because, it brings in decimal numbers too quickly. As usual, subtract 4 times 1^{st} row from 2^{nd} , 2 times 1^{st} row from 3^{rd} , 1 times 1^{st} row from 4^{th} :

$$\begin{pmatrix} 1 & 2 & 3 & 0 \\ 0 & -9 & -5 & 4 \\ 0 & -3 & -1 & 2 \\ 0 & -1 & -1 & 0 \end{pmatrix}$$

Continued

Switch 2^{nd} and 4^{th} row; then multiply the new 2^{nd} row by -1 :

$$\begin{pmatrix} 1 & 2 & 3 & 0 \\ 0 & -1 & -1 & 0 \\ 0 & -3 & -1 & 2 \\ 0 & -9 & -5 & 4 \end{pmatrix} \mapsto \begin{pmatrix} 1 & 2 & 3 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & -3 & -1 & 2 \\ 0 & -9 & -5 & 4 \end{pmatrix}$$

Add 3 times 2^{nd} row to 3^{rd} and 9 times 2^{nd} row to 4^{th} :

$$\begin{pmatrix} 1 & 2 & 3 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 2 & 2 \\ 0 & 0 & 4 & 4 \end{pmatrix}$$

Continued

Subtract, 2 times 3rd row from 4th:

$$\begin{pmatrix} 1 & 2 & 3 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

This matrix is essentially in row Echelon form.

Continued

- ▶ So, a Basis of the row space of A is $\{(1, 2, 3, 0), (0, 1, 1, 0), (0, 0, 2, 2)\}$
- ▶ $\text{rank}(A) = 3$
- ▶ $\text{Nullity}(A) = 4 - 3 = 1$
- ▶ To compute $N(A)$ and a basis of $N(A)$, we solve the homogeneous system for the above reduced matrix, which we do in the next frame.

Continued

$$\begin{pmatrix} x_1 & +2x_2 & +3x_3 & & = 0 \\ 0 & x_2 & +x_3 & & = 0 \\ 0 & 0 & 2x_3 & +2x_4 & = 0 \end{pmatrix}$$

$$\text{With } x_4 = t \quad \begin{cases} x_1 = -2t + 3t = t \\ x_2 = t \\ x_3 = -t \\ x_4 = t \end{cases}$$

Continued

The null space of A :

$$N(A) = \left\{ \begin{pmatrix} t \\ t \\ -t \\ t \end{pmatrix} : t \in \mathbb{R} \right\}$$

Since $\text{nullity}(A) = 1$, we are looking for one basis element. A basis of $N(A)$ is (obtained by taking $t = 1$):

$$\left\{ \begin{pmatrix} 1 \\ 1 \\ -1 \\ 1 \end{pmatrix} \right\}$$

Example 4.6.7

Let
$$A = \begin{pmatrix} 4 & -1 & 2 \\ 2 & 3 & -1 \\ 6 & 2 & 1 \end{pmatrix}$$

- ▶ Give basis of the row space of A
- ▶ Compute $\text{rank}(A)$
- ▶ Compute $\text{Nullity}(A)$
- ▶ Give a basis of the null space $N(A)$.

Continued

Solution. First, reduce A to an, essentially, row echelon form.
Switch first and second row of A :

$$\begin{pmatrix} 2 & 3 & -1 \\ 4 & -1 & 2 \\ 6 & 2 & 1 \end{pmatrix}$$

Subtract, 2 times first row from second and 3 times first row from third:

$$\begin{pmatrix} 2 & 3 & -1 \\ 0 & -7 & 4 \\ 0 & -7 & 4 \end{pmatrix}$$

Continued

Subtract second row from third:

$$\begin{pmatrix} 2 & 3 & -1 \\ 0 & -7 & 4 \\ 0 & 0 & 0 \end{pmatrix}$$

This matrix is, essentially in row Echelon form.

Continued

- ▶ So, a Basis of the row space of A is $\{(2, 3, -1), (0, -7, 4)\}$
- ▶ $\text{rank}(A) = 2$
- ▶ $\text{Nullity}(A) = 3 - 2 = 1$
- ▶ To compute $N(A)$ and a basis of A , we solve the reduced system above, which we do in the next frame.

Continued

Subtract second row from third:

$$\begin{cases} 2x + 3y - z = 0 \\ -7y + 4z = 0 \end{cases} \implies \begin{cases} x = -\frac{3}{2}y + \frac{1}{2}z = -\frac{5}{14}z \\ y = \frac{4}{7}z \end{cases}$$

Taking $z = t$, we have

$$N(A) = \left\{ \begin{pmatrix} -\frac{5}{14}t \\ \frac{4}{7}t \\ t \end{pmatrix} : t \in \mathbb{R} \right\} = \left\{ \begin{pmatrix} -\frac{5}{14} \\ \frac{4}{7} \\ 1 \end{pmatrix} t : t \in \mathbb{R} \right\}$$

Continued

Since $\text{nullity}(A) = 1$, there is only one element in the basis of $N(A)$, which can be obtained by taking $t = 1$. A basis of $N(A)$ is:

$$\left\{ \begin{pmatrix} -\frac{5}{14} \\ 4 \\ 7 \\ 1 \end{pmatrix} \right\}$$

Alternately, we could take $t = 14$ and another basis of $N(A)$ would be

$$\left\{ \begin{pmatrix} -5 \\ 8 \\ 14 \end{pmatrix} \right\}$$