Chapter I Introduction §1.2 Preliminaries and Classification of DEs

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Equations from §1.1

We recall the equations discussed in §1.1.

► Falling Object Models:

$$\begin{cases} m\frac{dv}{dt} = mg - \gamma v & \text{with } m = 10, \\ 10\frac{dv}{dt} = 9.8 - 2v & g = 9.8, \ \gamma = .2 \\ OR & \frac{dv}{dt} = 9.8 - .2v \end{cases}$$
 (1)

► Population Growth Model:

$$\begin{cases}
\frac{dp}{dt} = rp & \text{neglect other gains} \\
\frac{dp}{dt} = .5p - 450 & r = .5, \text{ other gain } 450
\end{cases} (2)$$

General First Order Equations:

$$\frac{dy}{dt} = f(t, y)$$
 where f is a function of t, y . (3)

The equations in §1.1 have been fairly simple, in the sense:

- All the DEs are of the form (3): $\frac{dy}{dt} = f(t, y)$. It involves only 1st derivative; and no higher order derivatives.
- ▶ For these DEs (1, 2), the right side f(t, y) are linear.
- ➤ Solving such DEs (3), mainly, involves nothing more than revisiting antiderivatives.

Solving the Growth Model

 \blacktriangleright We solve the population growth model ((1):

$$\frac{dp}{dt} = .5p - 450 \implies \frac{dp}{.5p - 450} = dt \tag{4}$$

- ▶ $\int \frac{dp}{.5p-450} = \int dt + C$, where C is an arbitrary constant.
- ▶ Substituting u = .5p 450 we get

$$\frac{du}{u} = .5 \int dt + C$$
 Or $\ln |u| = .5t + C$

$$|.5p - 450| = e^{.5t + C} = ce^{.5t}$$
 Or $p = 900 + ce^{.5t}$

where $c := \pm e^{C} > 0$ is an arbitrary constant.



Initial Value

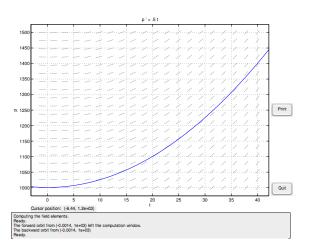
- $p = 900 + ce^{.5t}$ is a solution of (4), for all values of c. This would be called the General solution
- ▶ In the absence of further information, we cannot determine the value of *c*.
- Such extra information is provided, often, by giving the population size $p(t_0)$ at a particular time t_0 . For example, it may be given that p(0) = 1000. Such information, is called an initial condition.

▶ In case, p(0) = 1000, we have

$$1000 = p(0) = 900 + c, \quad c = 100$$

Finally, our particular solution is $p = 900 + 100e^{.5t}$

▶ In the next frame, compare the direction fields of the DE (1), with this solution $p = 900 + 100e^{.5t}$.



Solving such general equations

More generally, consider the initial value problem:

$$\begin{cases} \frac{dy}{dt} = ay - b \\ y(0) = y_0 \end{cases} \quad a, b \text{ are constants, and}$$
 (5)

 y_0 is (an) initial value of y, at time t = 0.

continued

(Trivial cases):

▶ If a = 0 then the equation is rewritten as

$$\left\{ \begin{array}{ll} \frac{dy}{dt} & = -b \\ y(0) & = y_0 \end{array} \right. \quad \textit{Solution} : \textit{exercise}$$

Assume $a \neq 0$ and ay - b = 0 then, $y = y(t) = \frac{b}{a}$. Then there is nothing to solve. We have

$$\begin{cases} \frac{dy}{dt} = 0 \\ y(0) = y_0 \end{cases} \qquad \left(Answer : y = y_0 = \frac{b}{a} \right)$$

continued

(The Non-Trivial case):

$$\begin{cases}
\frac{dy}{dt} = ay - b \\
y(0) = y_0
\end{cases}
\begin{cases}
a \neq 0, \\
ay - b \neq 0
\end{cases}$$
(6)

▶ We have $\frac{dy}{ay-b} = dt$. So, $\int \frac{dy}{ay-b} = \int dt + C$, where C is an arbitrary constant. So,

$$\int \frac{dy}{y - \frac{b}{a}} = a \int dt + C \Longrightarrow \ln \left| y - \frac{b}{a} \right| = at + C$$

continued

- Taking exponential: The general solution of (6) is: $y \frac{b}{a} = ce^t$ where $c = \pm e^C$ is also arbitrary
- ightharpoonup c = 0 corresponds to the equilibrium solution $y = \frac{b}{a}$.
- ▶ Using the initial values, we have $y(0) = y_0$: $y_0 \frac{b}{a} = c$
- ▶ So, the final solution of the initial value problem (6) is:

$$y = \frac{b}{a} + \left[y_0 - \frac{b}{a} \right] e^{at} \tag{7}$$

Standard Examples

Following are some of the standard examples:

- Mass of decaying mass (usually radio active). The Population Growth Model above, the amortization of an interest paying account. These are analogous.
- ► Motion of an ejected or falling body.

We discuss such examples subsequently.

Example 1: Decaying Mass

Statement: Let Q(t) denote the mass of some radio-active substance, at time t. It is known that such substances disintegrates at a rate proportional to the current mass Q(t). Write down a model, for this phenomenon.

- The rate of disintegration, at time t would be $\frac{dQ}{dt}$. According to the above model statement, $\frac{dQ}{dt}$ is proportional to Q(t).
- ▶ So, the model is $\frac{dQ}{dt} = -rQ(t)$, for some constant r > 0.
- ▶ By (6) and solution 7, with b = 0, a = -r, we have

$$Q(t) = Q(0)e^{-rt}$$



Statement: Now suppose initial mass is 1000 grams, which reduces to 900 grams in 10 hours. Compute r.

- We are given $\left\{ egin{array}{l} Q(0)=1000 \ \textit{gram} \\ Q(10)=900 \end{array}
 ight.$, at hour t.
- ► So, we have

$$900 = 1000e^{-10r}. \quad r = -\frac{\ln(.9)}{10} = .0105$$

ightharpoonup So, $Q(t) = 1000e^{-.0105t}$.

Example 2: Motion of a Falling Body

Statement: A missile has a vertical and a horizontal motion. For now, we only consider the vertical motion. Suppose such a missile of mass 1000 kg, is projected and the vertical drag is proportional to square of the velocity. We formulate the model for vertical velocity.

- Let v(t) denote the vertical velocity of the missile, at time t.
- ▶ The model of the falling body DE (1) was modified, by changing model on drag. By the model statement, the drag= γv^2 .

► So, the new model DE is

$$m\frac{dv}{dt} = mg - \gamma v^2 \tag{8}$$

▶ Recall $g = 9.81 \text{ meter}/s^2$. With m = 1000 kg. So, we have

$$\frac{dv}{dt} = 9.81 - \frac{1}{1000} \gamma v^2 \tag{9}$$

Statement: You recorded, the vertical acceleration $\frac{dv}{dt} = 0$, reduces to zero, when velocity $v(t) = 100 \; meter/sec$. We compute the drag constant γ .

► Substituting $\frac{dv}{dt} = 0$, v = 0, in (9),

$$0 = 9.81 - \frac{1}{1000}\gamma(100^2).$$

ightharpoonup So, $\gamma = .981$ and the model is

$$\frac{dv}{dt} = 9.81 - \frac{.981}{1000}v^2 = \frac{.981}{1000} (10000 - v^2)$$

► We separate variables (see §2.3):

$$\int \frac{dv}{v^2 - 10000} = -\frac{.981}{1000} \int dt + c \implies$$

$$\int \frac{1}{200} \left(\frac{1}{v - 100} - \frac{1}{v + 100} \right) dv = -\frac{.981}{1000} + c \implies$$

$$\frac{1}{200}\ln\left|\frac{v-100}{v+100}\right| = -\frac{.981}{1000} + c \Longrightarrow$$

$$\left| \frac{v - 100}{v + 100} \right| = Ce^{-.1962t}$$
 with $C = e^{200c} > 0$

► So,

$$\frac{v - 100}{v + 100} = Ce^{-.1962t}$$
 with $-\infty < C < \infty$

▶ Substituting v(0) = 0 we have C = -1

► So, the solution is given by

$$\frac{v-100}{v+100} = -e^{-.1962t} \Longrightarrow$$

$$v(t) = 100 - (v + 100)e^{-.1962t}$$

Next Level: Let h = h(t) denote the vertical distance of the missile, from the point of ejection, at time t. So,

$$\frac{dh}{dt} = v = v(t) = 100 - (v + 100)e^{-.1962t}$$

This equation can be solved to determine the height h(t), of the missile, at time t.

Example 3: Concentration

Statement: A water reservoir contains 10^6 gallons of water. The water is not acceptable for human consumption, due the level of chemicals in the water. The concentration of this chemicals is .01 gm/gallon. Pure water is added to the pond at the rate of 1,000 gallons/h. The well mixed water drains out of the pond at the same rate . Model the total quantity of chemicals in the pond and determine the concentration of the chemicals after one year.

Solution:

- Let Q(t) =quatity of the chemical in the pond, at time t.
- ► So, $Q(0) = .01 * 10^6 = 10^4$ gm.
- ▶ Part a): The rate of change

$$\frac{dQ}{dt} = -1000 * \frac{Q(t)}{10^6} = -\frac{Q(t)}{10^3}$$

► We can use the general solution solution (7) or rework it out. I will rework. We have

$$\int \frac{dQ}{Q} = -\int \frac{dt}{10^3} + c \quad c \text{ is a constant.}$$

$$\ln Q(t) = \frac{t}{10^3} + c.$$

So,
$$Q(t) = Ce^{-\frac{t}{10^3}}$$
 $C \ge 0$ is a constant Now, $Q(0) = 10^4 \Longrightarrow 10^4 = C$.
So, the solution is $Q(t) = 10^4 e^{-\frac{t}{10^3}}$

Finally, after one year, t = 365 * 24 = 8760. So,

$$Q(1 \text{ year}) = Q(8760) = 10^4 e^{-\frac{8760}{10^3}} = 10^4 e^{-8.760}$$

So, the concentration is

$$= \frac{Q(1 \text{ year})}{10^6} = \frac{10^4 e^{-8.760}}{10^6}$$
 per gallon. This is near zero.

§1.3 Classification based on no of ind. variables

Two broad classifications of DEs are as follows:

- When a DE involves only a single independent variable x (or t), then it is called an Ordinary DE (also called ODE). Chapter 2, 3 would be on ODE.
- When a DE involves more than one independent variables x_1, x_2, \ldots, x_n , then it is called a Partial DE (also called PDE). PDEs will not be covered in this course.

Classification based on number of unknown variables

- ► There may only be one unknown dependent variable y, to be determined. As in linear algebra, only one DE (plus initial value) is needed to determine y.
- There may also be more than one unknown dependent variables y₁, y₂, ..., ym, to be determined. As in linear algebra, a system of m (independent, in some sense) DE (plus initial values) are needed to determine y₁, y₂, ..., ym. They will be called a System of DEs. We will consider such systems in chapter 7.

Based on Order of derivatives

- DEs can be classified based on the highest order of derivation present.
 We will cover
 - ► First order DE (Chapter 2)
 - Second order DE (Chapter 3)

Linearity and non-linearity

▶ An ODE of order *n* is called linear, if it looks like

$$a_0(t) \frac{d^n y}{dt^n} + a_1(t) \frac{d^{n-1} y}{dt^{n-1}} + \cdots + a_{n-1}(t) \frac{dy}{dt} + a_n(t) y = g(t)$$

This is also written as:

$$a_0(t)y^{(n)} + a_1(t)y^{(n-1)} + \cdots + a_{n-1}(t)y^{(1)} + a_n(t)y = g(t)$$

 $a_i(t), g(t)$ are functions of the independent variable t.